# On the efficiency of normal form systems of Boolean functions EJCIM – Student presentations

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29 of March, 2018

## Preliminaries:

- Boolean functions,
- Clones,
- Normal Form Systems (NFSs)

## efficiency of NFSs

- How to measure efficiency?
- Classification of NFSs

## Suture work

- Representation of Boolean functions
- Efficient representations? Number of connectives
- Here: stratified formulas (connectives occur in constrained order) Variants: Jukna, 2012

- Median Normal Form: shown to be "more efficient" than DNF, CNF, etc.
- Other connectives/ Normal Form Systems?

Class composition of K with J:

$$K \circ J = \{f(g_1, \ldots, g_n): f \text{ n-ary in } K, g_1, \ldots, g_n \text{ m-ary in } J\}$$

### Definition

A clone is a class  $C \subseteq \Omega$  that contains all projections and satisfies  $C \circ C = C$ .

### Examples of clones:

- Clone of all projections:  $I_c$
- Clone of literals and constants:  $\Omega(1)$
- Clone of all conjunctions:  $\Lambda$
- Clone of all monotone functions: M
- Clone of all Boolean functions:  $\boldsymbol{\Omega}$

# Known results about (Boolean) clones:

- Clones constitute an algebraic lattice (E. Post, 1941).
  - Largest clone:  $\Omega$
  - Smallest clone: I<sub>c</sub>
- Each clone C is finitely generated: C = C(K), for some finite  $K \subseteq \Omega$  with:

$$\mathcal{C}(K) = \bigcap_{K \subset C \text{ clone}} C$$

• Each C has a dual clone  $C^d = \{f^d: f \in C\}$ , with

$$f^d(x_1,\ldots,x_n)=\overline{f(\overline{x_1},\ldots,\overline{x_n})}$$

# Classification of clones: Post's lattice

### Clone essentially associative: all essential functions are associative



Essentially associative

Essentially unary clones: generated by essentially unary functions

• 
$$I_c = \mathcal{C}(\{\}), I_0 = \mathcal{C}(\{0\}), I_1 = \mathcal{C}(\{1\}) \text{ and } I = \mathcal{C}(\{0,1\})$$

• 
$$I^* = \mathcal{C}(\{\neg\})$$
 and  $\Omega(1) = \mathcal{C}(\{\mathbf{0}, \mathbf{1}, \neg\})$ 

**Minimal clones:** clones that cover the clone  $I_c$  of projections

- $\Lambda_c = \mathcal{C}(\{\wedge\})$  of conjunctions and  $V_c = \mathcal{C}(\{\vee\})$  of disjunctions
- $L_c = C(\{\oplus\})$  of constant-preserving linear functions
- $SM = C(m_3)$  of self-dual  $(f = f^d)$  monotone functions

## Known results about composition of clones:

- $C_1 \circ C_2$  of clones is **not** always a clone:  $I^* \circ \Lambda$  is not a clone
- Composition of clones completely described by Couceiro, Foldes, Lehtonen (CFL2006)
- All factorizations of  $\Omega$  into a composition of "prime" clones (CFL2006)
- All factorizations of  $\Omega$  into a composition of minimal clones (CFL2006)

## (Descending) Irredundant Factorizations of Ω:

- **DNF**:  $\Omega = V_c \circ \Lambda_c \circ I^*$
- **CNF**:  $\Omega = \Lambda_c \circ V_c \circ I^*$
- **PNF**:  $\Omega = L_c \circ \Lambda_c \circ I$
- **PNF**<sup>d</sup>:  $\Omega = L_c \circ V_c \circ I$
- **MNF**:  $\Omega = SM \circ \Omega(1)$

Each corresponds to a normal form system (NFS)

Connectives  $\alpha_1, \ldots, \alpha_n$ 

Set of terms  $T(\alpha_1 \cdots \alpha_n)$  contains:

- All variables,
- All constant symbols,
- All terms  $\alpha_k(t_1, \ldots, t_{ar(\alpha_k)})$  if  $t_i$  are terms

The connectives are taken in order!







are not in the same NFSs!

٠	$\boldsymbol{M}=\boldsymbol{\mathit{T}}(m_{3}\neg)$
٩	$\mathbf{M}_{2n+1} = T(m_{2n+1}  \neg)$
٩	$\mathbf{S} = T(\uparrow)  (NAND)$
٩	$\mathbf{S}^d = T(\downarrow)  (NOR)$
٩	$\mathbf{D} = T(\vee \land \neg)$
٩	$\mathbf{C} = \mathcal{T}(\land \lor \neg)$
۰	$\mathbf{P} = T(\oplus \wedge)$
•	$\mathbf{P}^d = T(\oplus \lor)$

Median NF 2n+1-MNF Sheffer NF Peirce NF DNF CNF Reed-Muller NF Polynomial Dual NF

A: NFS, FA: set of formulas of A

The **A**-complexity of a Boolean function *f* is

$$C_{\mathbf{A}}(f) := \min\{|\phi|: \phi \text{ represents } f \text{ and } \phi \in F_{\mathbf{A}}\}$$

**NB:** Members of  $\Omega(1)$  are not counted in  $|\phi|$ 

### Example:

$$\begin{split} \mathbf{M} &: \phi = \mathsf{m}_3(x_1, x_2, x_3) \quad \text{and} \quad C_{\mathbf{M}}(\mathrm{MAJ}_3) = 1 \\ \mathbf{D} &: \phi = (x_1 \land x_2) \lor (x_1 \land x_3) \lor (x_2 \land x_3) \quad \text{and} \quad C_{\mathbf{D}}(\mathrm{MAJ}_3) = 5 \\ \mathbf{C} &: \phi = (x_1 \lor x_2) \land (x_1 \lor x_3) \land (x_2 \lor x_3) \quad \text{and} \quad C_{\mathbf{C}}(\mathrm{MAJ}_3) = 5 \\ \mathbf{P} &: \phi = \oplus_3(x_1 \land x_2, x_1 \land x_3, x_2 \land x_3) \quad \text{and} \quad C_{\mathbf{P}}(\mathrm{MAJ}_3) = 4 \\ \mathbf{P}^d &: \phi = \oplus_3(x_1 \lor x_2, x_1 \lor x_3, x_2 \lor x_3) \quad \text{and} \quad C_{\mathbf{P}^d}(\mathrm{MAJ}_3) = 4 \end{split}$$

An **NFS A** is polynomially as efficient as **B**, denoted  $\mathbf{A} \leq \mathbf{B}$ , if there is a polynomial *p* with integer coefficients such that

$$C_{\mathbf{A}}(f) \le p(C_{\mathbf{B}}(f))$$
 for all  $f \in \Omega$ 

**NB:**  $\leq$  is a *quasi-ordering* of **NFS**s

If  $A \not\preceq B$  and  $B \not\preceq A$  holds, then A and B are incomparable

If  $A \preceq B$  but  $B \not\preceq A$ , then A is polynomially more efficient than B

If  $A \leq B$  and  $B \leq A$ , then A and B are equivalently efficient  $(A \sim B)$ 

# Motivation

## Theorem (CFL2006)

- (1) D, C, P, and  $P^d$  are incomparable
- **2** M is polynomially more efficient than D, C, P, and  $P^d$

## **Definition** (to be justified below)

- An NFS A is efficient if  $A \sim M$ .
- Problem 1. Existence of other NFSs? E.g.: (other connectives)
- Problem 2. Classification of NFSs in terms of efficiency
- Problem 4. How to obtain optimal representations in each efficient NFS? E.g.: optimal median normal forms?

# Locating efficient NFSs...



### Theorem

NFSs based on a single nontrivial connective are efficient

### Theorem

The choice of connective does not impact efficiency (ex.:  $T(m_3 \neg) \sim T(m_5 \neg)) / 1$  (



#### Theorem

M is optimal: there is no NFS strictly below it

NB: justifies the definition of efficiency!

Property of the ternary median: pivotal function!

### Definition

Median decomposition scheme (Marichal, 2009): f a monotone Boolean function; for any  $k \in \{1, ..., ar(f)\}$ :

$$f(\mathbf{x}) = \mathsf{m}(f(\mathbf{x}_k^0), x_k, f(\mathbf{x}_k^1))$$

ightarrow Provides efficient (i.e. polynomial at most) ways to rewrite terms  $\mathbf{A} 
ightarrow \mathbf{M}$ 

Example: 
$$f(x, y, z) = (x \land y) \land z$$
.

From the median decomposition scheme:

$$f(x, y, z) = m(f(0, y, z), x, f(1, y, z)),$$

$$f(x, y, z) = \mathsf{m}(\mathsf{m}(\mathsf{m}(0, z, 1), y, \mathsf{m}(0, z, 0)), \underset{\uparrow}{\mathsf{x}}, \mathsf{m}(\mathsf{m}(0, z, 0), y, \mathsf{m}(0, z, 1)))$$

 $\rightarrow$  Composition without (too many) repeted subterms!

Finer comparison of efficient NFSs

 $\textbf{2} \ \ \mathsf{Redundant} \ \mathsf{factorizations} \ \mathsf{of} \ \Omega$ 

**③** NFSs to represent functions from a smaller clone than  $\Omega$  (e.g. M)

**4** Representation of multi-valued operations  $\{0, \ldots, n\}^k \rightarrow \{0, \ldots, n\}$ 

Median normal forms (in M)

- Decision problems: minimization, rewriting
- Structural description

Merci de votre attention !

Thank you for your attention!

Grazie mille per la vostra attenzione!

